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This is an accepted manuscript version of an article by Alex Bush, et.al. 2017. **Connecting Earth observation to high-throughput biodiversity data**. *Nature Ecology & Evolution*, 1: 0176.
DOI: <https://doi.org/10.1038/s41559-017-0176>



1 Connecting Earth Observation to High-Throughput

2 Biodiversity Data

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54 **Preface**

55 There is much interest in using Earth Observation (EO) technology to track biodiversity,
56 ecosystem functions, and ecosystem services, understandable given the fast pace of
57 biodiversity loss. However, because most biodiversity is invisible to EO, EO-based
58 indicators could be misleading, which can reduce the effectiveness of nature
59 conservation and even unintentionally decrease conservation effort. We describe an
60 approach that combines automated recording devices, high-throughput DNA
61 sequencing, and modern ecological modelling to extract much more of the information

62 available in EO data. This approach is achievable now, offering efficient and near-real-
63 time monitoring of management impacts on biodiversity and its functions and services.

64 **Meeting the Aichi Biodiversity Targets**

65 From Google Earth to airborne sensors, the Copernicus Sentinels, and cube satellites,
66 Earth Observation is undergoing a rapid expansion in capacity, accessibility, resolution,
67 and signal-to-noise ratio, resulting in a recognised shift in our capability for using
68 remote-sensing technologies to monitor biophysical processes on land and water¹⁻³.
69 These advances are motivating calls to use Earth Observation products to manage our
70 natural environment and to track progress toward global and national policy targets on
71 biodiversity and ecosystem services⁴⁻⁶. Foremost among these policies are the Strategic
72 Plan for Biodiversity and the Aichi Biodiversity Targets, which were adopted in 2010 by
73 the Parties to the Convention on Biological Diversity (CBD) to "take effective and urgent
74 action to halt the loss of biodiversity in order to ensure that by 2020 ecosystems are
75 resilient and continue to provide essential services..."⁷. The United Nations Sustainable
76 Development Goals⁸ now include some of the Aichi Targets, and the 2015 Paris
77 Agreement has reiterated the commitments of the UN Framework Convention on
78 Climate Change to reducing emissions from deforestation and forest degradation

79 (REDD+) and to securing non-carbon benefits, which include biodiversity and ecosystem
80 services⁹.

81 However, we have struggled to track and report progress toward the Aichi Targets in a
82 standardised and comprehensive way¹⁰. Although almost two-thirds of the CBD Parties
83 have updated their National Biodiversity Strategies and Action Plans to reflect the 2010
84 revisions, many still do not contain measurable indicators on the state of biodiversity, let
85 alone ecosystem services. This lack of quantification conceals the impacts of policy and
86 management interventions on biodiversity and ecosystem functions and services¹¹. The
87 difficulty of designing indicators¹²⁻¹⁴ has prompted an international consortium of
88 biodiversity scientists called GEO BON (Group on Earth Observations' Biodiversity
89 Observation Network) to propose a framework of Essential Biodiversity Variables¹⁵, with
90 the aim of setting minimum standards of coverage to ensure informativeness and to
91 harmonise disparate local measures so that biodiversity and ecosystem data can be
92 compared over space and time. The Essential Biodiversity Variables thus measure the
93 'state of biodiversity' at multiple levels: genetic composition, species populations,
94 species traits, community composition, ecosystem structure, and ecosystem function¹⁵.

95 Although it was originally envisioned that most of the variables (genetic to community
96 composition) would be scaled up from "intensive *in-situ* measurements"¹⁵ taken on the

97 ground, such measurements are costly and difficult because they are traditionally
98 gathered by visual and aural detection of plants and animals in the wild (preceded by
99 months or years of observer practice) and by mass collection of organisms (followed by
100 months of identification from morphology), so that data collection is slowed by human-
101 caused bottlenecks in sampling and taxonomy¹⁶.

102 As a result, attention is now being focused on designing 'Satellite Remote Sensing-
103 Essential Biodiversity Variables' (SRS-EBVs) to enable cost-effective and global-scale
104 monitoring^{5,6,12}. The problem here is that only a few Earth Observation products can be
105 mapped directly to Essential Biodiversity Variables and then to Aichi Targets, because
106 these products primarily measure gross vegetation and landscape metrics, such as land
107 cover and phenology⁴. For example, Pettorelli et al.¹² found only two Earth Observation
108 products (net primary productivity and fire incidence) that could serve as Essential
109 Biodiversity Variables for the Sahara, despite this biome's suitability for remote sensing
110 due to its visible biodiversity hotspots, remoteness, and availability of long time series.
111 Many of the Aichi Targets require data with species-level resolution, either because some
112 species are direct policy targets (e.g. Target 9: "invasive species controlled or eradicated")
113 or because species compositional data define the metric (e.g. Target 11: "protected areas
114 are ecologically representative and conserved effectively").

115 Clearly, a radically new approach is required if progress towards the Aichi Targets is to
116 be accelerated, one that is robust, widely affordable, and can record stocks and changes
117 in biodiversity and ecosystem services consistently, continuously, and at high resolution
118 over large geographic scales. Here, we present such an approach in a framework that
119 exploits recent efficiency gains and analytical breakthroughs in sensors, computation,
120 ecology, taxonomy, and genomics (**Figure 1, Box 1**).

121

122

123 **Box 1. Inferring a Hidden Ecosystem Function from Space**

124 Large-bodied Amazonian monkeys are responsible for a key ecosystem function: they are
125 the primary dispersers of large seeds, which are associated with more carbon-dense tree
126 species. Peres et al.¹⁷ have proposed that this function boosts forest carbon storage. The
127 idea can be tested by using Earth Observation data and public records to map human
128 settlements and transport corridors and predict where monkey populations have
129 declined through hunting^{17,18}. We can then use on-the-ground sampling and airborne
130 sensors to test whether forests that have had longer exposure to hunting lack monkey
131 populations and have more low-carbon-density tree species dispersed by wind and birds.
132 In short, by combining Earth-Observation-derived maps of human activity with empirical
133 observations of the response of primate populations to that activity, it should be

134 possible to map and track an ecosystem function (large-seed dispersal) that is invisible to
135 satellites but contributes to an important ecosystem service (climate regulation).

136

137

138 **From Point Samples to Continuous Maps**

139 Instead of trying to map Earth Observation (EO) products directly to biodiversity, as
140 encapsulated by SRS-EBVs^{4-6,12}, we propose to extract more information from EO data by
141 interpolating biodiversity point samples to build continuous landscape maps of species
142 distributions (**Figure 1**)¹⁹. Because it is species that are mapped, it then becomes possible
143 to layer on the vast biological knowledge that we have collectively built up over decades
144 of research, including historical distributions, phylogenetic relationships, and knowledge
145 of species traits and interactions to infer, map, and track the distributions of ecosystem
146 functions and services (**Box 1**). This approach, which we call here **CEOBE** (Connecting
147 Earth Observation to Biodiversity and Ecosystems), is possible because of (1) major
148 advances in EO sensitivity and capacity, (2) more efficient techniques to collect
149 biodiversity data on the ground, and (3) modern community-analysis models from
150 statistical ecology. We now review each of these advances, with additional detail in
151 Supplementary Information.

152 **The New Era of Earth Observation**

153 There are ten times as many satellites in operation now as there were in the 1970s, a
154 result of increasing sensor longevity and a six-fold increase in launches²⁰. Spatial
155 resolution has improved to less than 1 m in both optical and radar sensors. Data
156 continuity is also being maintained, most directly by the launch of NASA's Landsat 8 in
157 2013, which extends and technically enhances the 40-year Landsat record of medium-
158 resolution, multispectral surface observations²¹. Data continuity is a key factor in
159 understanding changes in biodiversity, as threats to biodiversity impact at a range of
160 scales and often across lengthy timespans²².

161 The long-term Landsat record is being enhanced by new satellite systems and multiple
162 sensors in a global network, a 'virtual constellation' that may help overcome problems in
163 terrestrial monitoring from single sensors². As part of the Copernicus program, the ESA
164 Sentinel satellites are the latest addition to the global network. With six missions planned
165 and the first three launched, the Sentinels have radar, optical sensors, radiometers, and
166 spectrometers with different goals²³. Sentinel-1, the radar satellite, and Sentinel-2, the
167 superspectral high-resolution mission, are of particular interest to biodiversity
168 monitoring, with long-term continuity of measurements, global coverage, and quick
169 revisit times^{24,25}.

170 There have also been developments in hyperspectral sensors with EnMAP, HypSI, IRI,
171 PRISMA, and FLEX imaging spectrometer missions planned¹. In addition, airborne data
172 collection using high-resolution 3D airborne laser scanning is complementing spectral
173 information with structure²⁶. Swarms of commercial cube satellites and the use of drones
174 to carry sensors are additional significant steps that complement these large-scale
175 programs (**Supplementary Note 1** "Earth Observation technology").

176 The increase in spatial resolution in the new sensors implies greater precision because
177 reference measurements taken within meter-scale plots on the ground can be matched
178 directly to meter-scale pixels²⁷. This in turn improves the ability of EO to recognise
179 spatial gradients and boundaries.

180 Two additional factors affect the utility of remote sensing data for understanding
181 biodiversity change (**Supplementary Note 2** "Biodiversity and ecosystem information in
182 EO data"): affordability and access²². There has been a cultural shift, with free open
183 access on the rise. The opening of the Landsat archive in 2008 was a monumental
184 development²⁸, with ESA's Copernicus program following suit. Data access also refers to
185 the ability of users to retrieve, manipulate, and extract value from EO data. Cloud
186 computing and toolboxes are making these processes manageable, even with large data
187 archives.

188 The availability of copious EO data that have been shown in multiple studies to correlate
189 closely with on-the-ground measures of ecosystem structure, habitat condition, and even
190 animal communities (**Supplementary Note 2**) might suggest that remote sensors can be
191 used directly to define environmental indicators, but we must acknowledge that we are
192 still in the early stages of understanding how biodiversity delivers ecosystem functions
193 and services, and how they all respond to exogenous change. Directly observing
194 functional diversity is a partial solution but only with visible biodiversity such as
195 vegetation²⁶. Thus, the challenge is to find ways to exploit the high efficiency and
196 information content of EO data while not falling prey to *reification fallacy* (**Box 2**), which
197 can arise when convenient but incomplete indicators are made available^{29,30}. Our
198 institutions and reporting systems then retain the option to add and respond to new
199 knowledge.

200

201

202 **Box 2. The Perils of Convenient Indicators**

203 If we rely too directly on EO data, we run the risk of *reification fallacy*, in which a mere
204 indicator of a policy target itself ends up the target. Reification fallacy can reduce or
205 narrow conservation effort³¹ and can crowd out future discoveries³². For example, while
206 remote sensing is an efficient and direct way to measure forest *cover* (Aichi Target 5:

207 reducing the loss rate of natural habitats), using forest cover and phenology to measure
208 the contribution of biodiversity to carbon stocks (Target 15)⁴ would ignore taxa invisible
209 to satellites and could thus result in policymakers failing to exert the additional effort
210 that is required to conserve saprotrophic fungal diversity, seed-dispersing mammals, and
211 the seemingly inconsequential isopod, all of which have been implicated in boosting
212 carbon storage^{17,33,34}. More generally, land-cover class, which is a common EO-indicator,
213 is a highly error-prone way to map and assess the complex processes supporting
214 ecosystem services³⁵. In short, convenient EO products could lead policymakers to focus
215 only on that portion of biodiversity and ecosystem services that is directly observed by
216 remote sensing, ignoring the rest.

217

218 **High-Throughput Biodiversity Measurement**

219 Most biodiversity, whether animal, fungal, plant, or microbial, and its many functions and
220 services, is invisible to EO and will remain so for some time. But a growing number of
221 efficient technologies are available for detecting and identifying biodiversity on the
222 ground^{36,37} (**Supplementary Note 3** "Biodiversity technology"). Automated bioacoustic
223 and camera-trap recording devices (ARDs) can run continuously for weeks and
224 accumulate thousands of records of invertebrates, birds, fish, reptiles, amphibians, and

225 mammals, and thus allow extended sampling of large areas at low workloads³⁸⁻⁴².

226 Alternatively, high-throughput DNA sequencers can be used in metabarcoding or

227 metagenomic pipelines to detect and identify anywhere from one to thousands of

228 species at a time from mass-collected, bulk samples of organisms (e.g. 'biodiversity

229 soups'⁴³), or from 'environmental DNA,' which is DNA liberated into the environment in

230 the skin, hair, mucous, saliva, sperm, eggs, exudates, faeces, urine, blood, spores, root

231 fragments, leaves, fruit, pollen, or rotting body parts of their original owners^{44,45} (**Figure**

232 **2, Supplementary Note 3**). Multiple studies have now shown that metabarcode datasets

233 reflect high-quality, morphologically identified biodiversity datasets sufficiently closely to

234 allow correct management decisions, given best-practice protocols and controls⁴⁶⁻⁵¹.

235 The taxonomic identities, phylogenetic affinities, functional genes⁵², spectral properties

236 (of visible vegetation^{26,53,54}), and/or co-occurrence patterns⁵⁵ of the detected species can

237 be used to parameterise process-based production functions for ecosystem services⁵⁶⁻⁵⁸

238 (**Figure 1**). For instance, the species identities and biomasses of wild bees identified

239 metagenomically from bulk samples⁵⁹ could be combined with flower-use observation

240 data⁶⁰ and detailed vegetation classification from EO to infer the availability and nature

241 of local pollination services. Metagenomic data matched to identified species can be

242 particularly powerful when the impacts of species loss on ecosystem function are not

243 random, evidence that has previously relied on intensive field sampling, e.g. in tropical
244 freshwater⁶¹ and marine benthic communities⁶².

245 **Statistical Modelling as the Bridge**

246 Earth Observation technology can produce large-scale, fine-resolution maps and dense
247 time series of a wide range of biophysical variables (**Supplementary Note 1 and 2**), but
248 it is difficult to translate the biophysical variables into biodiversity information. In
249 contrast, ARDs and DNA sequencing are capable of generating large amounts of
250 biodiversity information at species- or even individual-level resolution^{63,64}, but only from
251 point samples (**Supplementary Note 3**). Modern methods of statistical modelling allow
252 us to interpolate these point samples to build continuous species maps and to estimate
253 emergent metrics such as richness and dissimilarity⁶⁵⁻⁶⁸, potentially also including
254 estimates of species abundance or biomass, depending on the sampling and analytical
255 methods used (**Supplementary Note 4** "Statistical modelling").

256 The three approaches with immediate potential are *Joint Species Distribution Models*⁶⁹⁻⁷²
257 (including *Latent Variable Models*), *Community Occupancy-Detection Models*⁷³, and
258 *Generalised Dissimilarity Models*^{65,74} (**Figure 3, Supplementary Note 4**). Each approach
259 starts with a site-by-species matrix, from data that have been collected by ARDs or been
260 generated via metabarcoding or metagenomics (**Figure 2, Supplementary Note 3**), plus

261 any existing species distribution data. If some species are not detected, repeat sampling
262 can be used to infer missing occurrences⁷³. The site-by-species matrix is then paired with
263 a corresponding site-by-environmental-covariate matrix, generated from continuous EO
264 data plus any relevant geographical layers, and the two datasets are combined
265 statistically to infer the joint distributions of multiple species across entire regions
266 (**Figure 3, Supplementary Note 4**). All three approaches also provide a rigorous
267 framework for quantifying sources of uncertainty and have already been applied
268 successfully to conventionally acquired datasets (**Box 3**).

269

270

271 **Box 3. Current Practice in Community Modelling**

272 Ovaskainen et al.⁷¹ used a joint species distribution model to predict the distributions of
273 55 butterfly species scored for presence/absence on a grid of 2609 10 X 10-km cells
274 across Great Britain that had been sampled from 1995-1999 in a large citizen-science
275 project. The model was successfully parameterised with a training dataset of just 300
276 cells and four environmental covariates (degree-days and three types of vegetation
277 cover), plus spatially structured latent variables. Latent variables use observed species
278 subgroupings to detect the effects of unmeasured environmental filters or species
279 interactions such as competition. The parameterised model was used to predict butterfly

280 communities in the testing dataset, which consisted of the remaining 2309 grid cells.

281 Together, the measured and latent variables explained an average of 42% of the variance

282 in species occurrence (with medium-prevalence species more accurately predicted), and

283 the two most dominant latent variables revealed a north-south gradient in species

284 composition, with especially distinct communities in the southeast and northwest.

285 Species richness per grid cell was accurately predicted, and the model's ability to

286 discriminate presence and absence was high (mean AUC = 0.91).

287 Kéry and Royle⁷⁵ used community-occupancy modelling to analyse the 2001 Swiss

288 breeding-bird survey while accounting for variation in detectability due to season, site,

289 and species effects. The dataset consisted of 254 1-km² grid cells, each visited three

290 times. The fitted model predicted each species' probability of occurrence as a function of

291 site elevation and forest cover, as well as variance in the uncertainty of occurrence

292 estimates, making it possible to estimate species distributions across the landscape and

293 confidence in those estimates. Parameter estimates were naturally less precise for rare

294 species, but information could be 'borrowed' from data-rich species to increase the

295 precision of predictions for rare species. These procedures were able to compensate for

296 the fact that only 134 total bird species had been detected in the survey, which is less

297 than the true total of 163 species known to breed regularly in Switzerland, plus 22

298 occasional residents (the testing dataset). The occupancy-corrected model estimated that
299 between 1 and 11 species had been overlooked per grid cell and thus, that the true total
300 in 2001 was 169 species.

301 Mokany *et al.*⁷⁶ applied Generalised Dissimilarity Modelling (GDM) to a dataset of 2330
302 expert surveys of New Zealand land snails, which recorded 845 of 998 known species.
303 The GDM was parameterised with a training dataset of 2280 surveys and fourteen
304 environmental variables and explained 57% of the variation in beta diversity. In addition,
305 a generalised additive model parameterised on the training dataset explained 27% of the
306 variation in species richness (after scaling the 20 x 20-m survey quadrats to match the
307 area of modelling units (200 x 200-m); see discussion of scaling in **Supplementary Note**
308 **4**). Finally, the outputs were combined using a procedure called DynamicFOAM to assign
309 snail species to communities across New Zealand. Error was assessed by predicting
310 compositions in a testing dataset of 50 sites that had been held out of the model. On
311 average, the model was able to predict half the species that had been observed in each
312 cell, and the predicted total occupancy area per species was highly correlated with the
313 number of quadrat occurrences (Pearson's $r = 0.902$). When quadrats were pooled into
314 groups of 3 to 400 to reduce sampling stochasticity, predicted species richnesses almost
315 perfectly explained observed richnesses ($R^2 = 0.99$).

316

317

318 By mapping species distributions as the primary output, we do not lock ourselves into an
319 arbitrary set of convenient indicators, and ongoing discoveries on the relationship
320 between biodiversity and function, which are typically carried out at the species level, can
321 be added. As an illustration, the species diversity of wood-decaying fungi in natural
322 forests is notoriously difficult to assay but can be predicted in part by the volume and
323 species diversity of the stock of dead wood on the ground⁷⁷, and these environmental
324 covariates are partially quantifiable via airborne LiDAR sensors (**Supplementary Note**
325 **1**)⁷⁸, thus allowing EO-based inference of the distribution and level of wood-decaying
326 fungal diversity. Subsequent and unrelated research has suggested that pieces of dead
327 wood inhabited by a higher diversity of fungal species decompose more slowly, possibly
328 due to more intense interference competition³⁴. Combining the two results suggests that
329 an EO-derived map of fungal species diversity could be used to contrast landscape
330 management options for how well they conserve saprotrophic fungal biodiversity and
331 thus enhance carbon storage.

332 Two further reasons for focusing on species-resolution maps as the primary output are
333 that the regional species pool (*gamma diversity*) and the biological dissimilarity of sites

334 (*beta diversity*) could contribute to maintaining functional stability^{58,79,80} and that species-
335 resolution outputs retain the option of aggregation to represent different aspects of
336 biodiversity, including higher-taxonomic, functional, and phylogenetic groupings⁸¹.
337 Many methods are also available to predict *individual* species ranges, and EO can help
338 improve their accuracy, as shown by an example⁸² combining MODIS satellite data with
339 environmental DNA to map an invasive diatom over a watershed [Target 9, invasive
340 species pathway identified] (**Supplementary Figure 3.1**). However, ecosystem functions
341 and services are rarely delivered by only one species, and simply summing the outputs of
342 individual models to simulate communities is computationally inefficient, statistically
343 flawed, and does not account for species interactions⁸³.

344 **From CEOBE to Aichi**

345 In essence, our argument is that new technologies make the new community-modelling
346 approaches (**Box 3, Figure 3**) widely feasible, especially in biodiversity hotspots, where it
347 is particularly difficult to generate large datasets. Larger numbers of environmental
348 covariates and species together increase explanatory power by providing a greater
349 breadth of predictors, and by exploiting latent variables and letting rare species 'borrow'
350 information^{42,75,84}, respectively. As a result, continuous streams of EO data can be more
351 powerfully interpreted to track biodiversity status and trends (**Figure 1**).

352 The predictive performance of fitted models can be cross-validated by rounds of
353 comparison with testing datasets that were either split from the model-training
354 dataset^{71,76} or derived from historical and expert knowledge⁷⁵, and thus, the adequacy of
355 the input data and sampling design, or conversely the degree of model uncertainty, can
356 be assessed *post hoc* (**Box 3**). The regularly updated biodiversity maps that are the
357 primary outputs of the CEOBE approach (**Figure 1**), plus the quantified uncertainty in
358 those maps, can then be incorporated into a larger process of structured decision
359 making and adaptive management⁸⁵⁻⁸⁷ to (1) identify likely consequences of proposed
360 actions by observing natural experiments that mimic those actions, (2) compare observed
361 results of management interventions against objectives, and (3) help identify and tackle
362 sources of uncertainty.

363 An early example of the CEOBE approach is given by Sollmann *et al.*⁴², who used
364 community-occupancy modelling to connect environmental covariates from the 5-m-
365 resolution RapidEye satellite to point-sample data from camera traps in three tropical-
366 forest logging concessions in Sabah, Malaysian Borneo, one of which has been managed
367 to reduced-impact-logging standards set by the Forest Stewardship Council (Aichi Target
368 7, sustainable management under forestry). The dataset consisted of detection events for
369 28 mammal species at 166 camera-trap stations, each station scored using EO data for

370 distance to water, distance to oil-palm plantation, and forest condition. Estimated
371 relationships between species occurrence and the three covariates were used to predict
372 species occurrence across the three reserves, with rare mammal species borrowing
373 information from more common ones. Species richness was estimated to be higher in
374 the FSC-certified reserve, particularly for threatened species (Target 12, improved
375 conservation status of threatened species). The percentage of area occupied, which could
376 indicate larger population sizes, was also estimated to be higher in the FSC-certified
377 reserve for the majority of species, including for some highly endangered species like the
378 Sunda pangolin *Manis javanica*. Finally, the modelled species richness maps were found
379 to correlate strongly with EO-estimated aboveground biomass at the large spatial grain
380 of whole reserves, but not at a finer resolution (potentially due to hunting at reserve
381 borders), further demonstrating the critical contribution of ground-level point samples
382 for linking pure-EO data to biodiversity.

383 The major remaining components of uncertainty relate to generalisability, because only a
384 single FSC-certified reserve was sampled; the applicability of results to arboreal species,
385 which tend to be detected more frequently in forests with disturbed canopy but are not
386 necessarily more widespread in these forests; and wide confidence intervals around
387 parameter estimates for some species as a consequence of sparse data and a fairly

388 complex hierarchical model. This example serves as a proof of concept that camera
389 trapping and occupancy modelling can be used to assess biodiversity conservation based
390 on species maps, and the approach has been incorporated in the ten-year forest
391 management plan and wildlife monitoring strategy for the FSC-certified area. Repeated
392 surveys will help to narrow uncertainties in the model, and a future power analysis is
393 planned to estimate the sampling effort required to detect trends and/or provide
394 estimates with a desired level of certainty⁸⁸.

395 Another example of the CEOBE approach is the use of Generalised Dissimilarity
396 Modelling to connect EO-derived metrics of habitat degradation and fragmentation^{89,90}
397 to over 300 million records of more than 400,000 species from the Global Biodiversity
398 Information Facility (www.gbif.org) and the Map of Life (mol.org)⁹¹. The GDM models
399 spatial turnover in biodiversity composition at 1-km-resolution globally, and by invoking
400 the assumption that terrestrial biodiversity declines according to the classical species-
401 area power function, the GDM estimates the proportion of biodiversity that has been
402 retained in each grid cell after habitat loss, based on the proportion of similar habitat
403 remaining unimpacted within the landscape⁹². This metric thus tracks whether rates of
404 loss, degradation, and fragmentation of natural habitats are being reduced (Aichi Target
405 5). Further, by combining this approach with a global database of protected-area

406 coverage (www.protectedplanet.net), it is possible to report progress against Target 11,
407 which aims for protected areas to cover areas of particular importance to biodiversity
408 and ecosystem services and to be ecologically representative and connected (see also
409 Ref. 93). An important caveat is that the biodiversity data in this case are historical in
410 nature and thus contain the taxonomic and sampling biases and constraints of the past
411 (**Box 2**). Ideally, the biodiversity data will transition to up-to-date, properly sampled, and
412 more taxonomically comprehensive point samples.

413 Of course, CEOBE outputs cannot contribute to all Aichi Targets, namely those that are
414 focused on policy, planning, and funding reform (Targets 2, 3, 4, 20), the conservation of
415 genetic cultivars (Target 13), the alleviation of climate-change pressures on coral reefs
416 (Target 10), benefits sharing (Target 16), and the integration of traditional knowledge
417 (Target 18). It also remains to be seen how well or poorly EO data reflect biodiversity in
418 aquatic ecosystems (Targets 6 and 11), although environmental DNA on its own is a
419 highly promising source of data on aquatic biodiversity. On the other hand, the efficient
420 production of biodiversity maps and open access to analytical pipelines will help to
421 disseminate the science base and technologies related to biodiversity (Target 19), and
422 could contribute to public awareness of efforts to conserve biodiversity (Target 1) and
423 improve the efficiency of national biodiversity planning (Target 17).

424 **Conclusions**

425 It is extremely difficult to identify all the species present in a location (*the Linnaean*
426 *challenge*), to delimit the geographic distributions of species (*the Wallacean challenge*),
427 and to quantify their responses to natural and anthropogenic environmental change (*the*
428 *Hutchinsonian challenge*)⁹⁴. A synergy of Earth Observation, automated recording
429 devices, high-throughput DNA sequencing, and modern statistical modelling can meet
430 these challenges by making it possible to scale up from data-rich but finite sets of point
431 samples to spatially continuous biodiversity maps, which are more informative than a few
432 convenient indicator species but still let us generate summary statistics to communicate
433 trends to decision-makers and the general public. The use of formal statistical
434 frameworks lets us quantify error, identify gaps in our understanding, objectively rank the
435 most likely pressures on biodiversity from multiple candidates, and increase the
436 robustness of change detection. Adding information on species interactions and
437 functions helps link biodiversity to ecosystem functions and services (**Box 1, Figure 1**) in
438 a process-based approach⁵⁶, rather than relying on crude estimates from land classes³⁵.
439 Finally, as DNA-based technologies mature, the same samples could track population-
440 genetic diversity^{64,95,96}.

441 A global, multi-resolution monitoring network is thus within our reach but will still
442 involve a number of challenges associated with technical capacity, computation and data
443 storage, and data standardisation. For every ecologically distinct region, there will be an
444 initial cost to collect data for model parameterisation, followed by a low level of
445 continuous sampling, which will be necessary for updating models and for surveillance
446 monitoring of environmental drivers that are invisible to EO, such as broad-spectrum
447 insecticides. The initial costs are probably best borne by governments, as part of their
448 commitment to the Convention on Biological Diversity, and there is great promise in
449 using citizen-science networks to collect standardised, bulk biodiversity samples over
450 large areas. A laudable example is the School Malaise Trap Program that recruited
451 hundreds of secondary-school science classes to collect arthropods across Canada
452 (malaiseprogram.com). Initial investment could also come from existing monitoring
453 budgets with the expectation that additional information content will compensate for
454 reduced sample numbers within existing programs⁸². The follow-up continuous sampling
455 requires steady funding streams, and the standardisation of the CEOBE approach meets
456 the needs of international certification schemes, such as REDD+, Climate, Community &
457 Biodiversity Standards, Forest Stewardship Council, and the Roundtable on Sustainable
458 Palm Oil, which all require the continuous monitoring of biodiversity and ecosystem

459 services. Biodiversity-offset payments to mitigate the impacts of development and
460 carbon emissions are also expected to provide funding streams, and standardised
461 assessments are needed to ensure that offsetting results in biodiversity net gain⁹⁷.

462 The CEOBE approach also depends on institutional support for the multidisciplinary
463 collaborations needed to generate, combine, analyse, and act upon data from disparate
464 disciplines (EO, ARDs, genomics, taxonomy and systematics, ecosystem functions and
465 services, statistics, and decision science), expertise that no single individual has^{12,30,98}.

466 Identifying causal determinants of species distributions needs a clear understanding of
467 phylogenetic structure and functional diversity, the ecological processes involved, and
468 what EO sensors can and cannot observe⁹⁹. Expert knowledge will also contribute to
469 sampling design and covariate selection so that the full breadth of environmental
470 conditions is captured, especially those not visible to EO.

471 On the other hand, collaborations need not be global. Political and social interests will
472 vary by region, and agencies should be encouraged to trial CEOBE within their
473 jurisdictions where there are clear opportunities to improve management, while also
474 enforcing the publication of primary data and analytical pipelines^{27,100}. The
475 Intergovernmental Platform on Biodiversity and Ecosystem Services (IPBES) could play an
476 important role as a global coordinating institution.

477 Resources for environmental management are always likely to be limited, but by doing
478 more with our expensively gained field data, we can take action more efficiently and
479 effectively. What is required now is leadership by governments and international
480 organisations to stimulate integrated research and to endorse the use of comprehensive
481 biodiversity information⁶.

482 **Acknowledgements**

483 This article is a product of the EO-BESS Working Group, organised by Heiko Balzter,
484 David Raffaelli, and Beth Cole and funded by the UK Natural Environment Research
485 Council. Individual author acknowledgements are in Supplementary Information.

486 **Author Contributions**

487 BC and HB led the sections on Earth Observation technology. KB and DWY led the
488 sections on Biodiversity technology. AB led the sections on Statistical modelling. AB, RS,
489 AW, OO, and DWY led the sections on case studies (Box 3 and CEOBE to Aichi). CM led
490 the Conclusions section. Figures were created by KB, AB, CC, and AZ. All authors
491 contributed to multiple rewrites, with a large contribution by DR. AB and DWY wrote the
492 first draft and supervised the work.

493 **Additional Information**

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495 **Competing Interests**

496 DWY and AV are co-founders of a private company that provides commercial
497 metabarcoding services.

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798 **Figure legends**

799 **Figure 1. CEOBE – Connecting Earth Observation to Biodiversity and Ecosystems. Top**

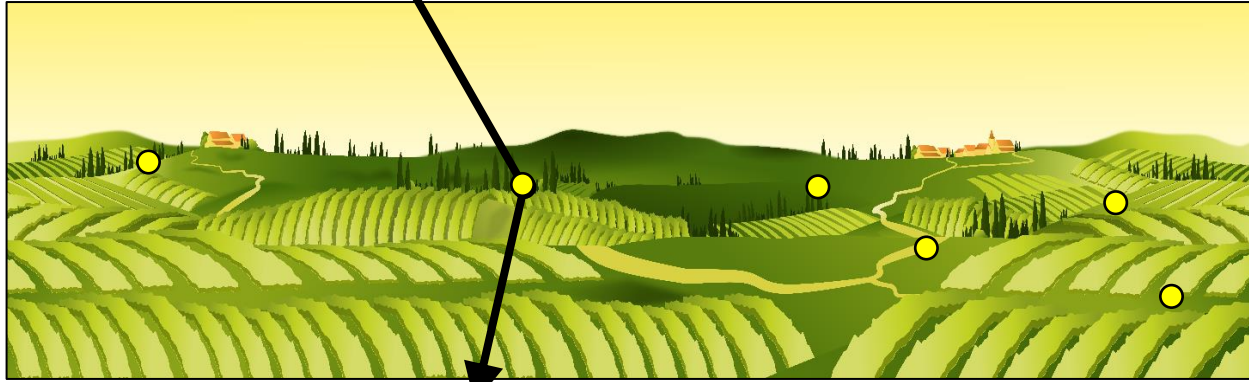
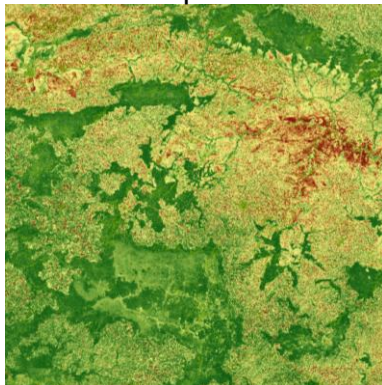
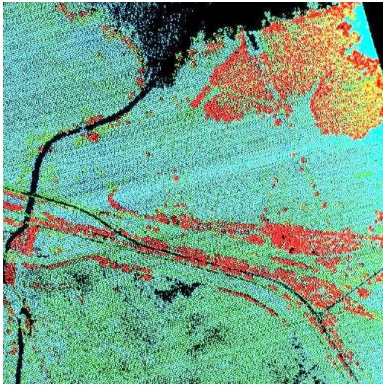
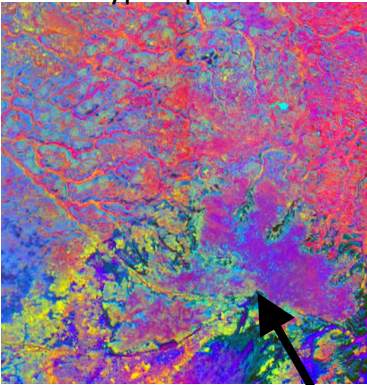
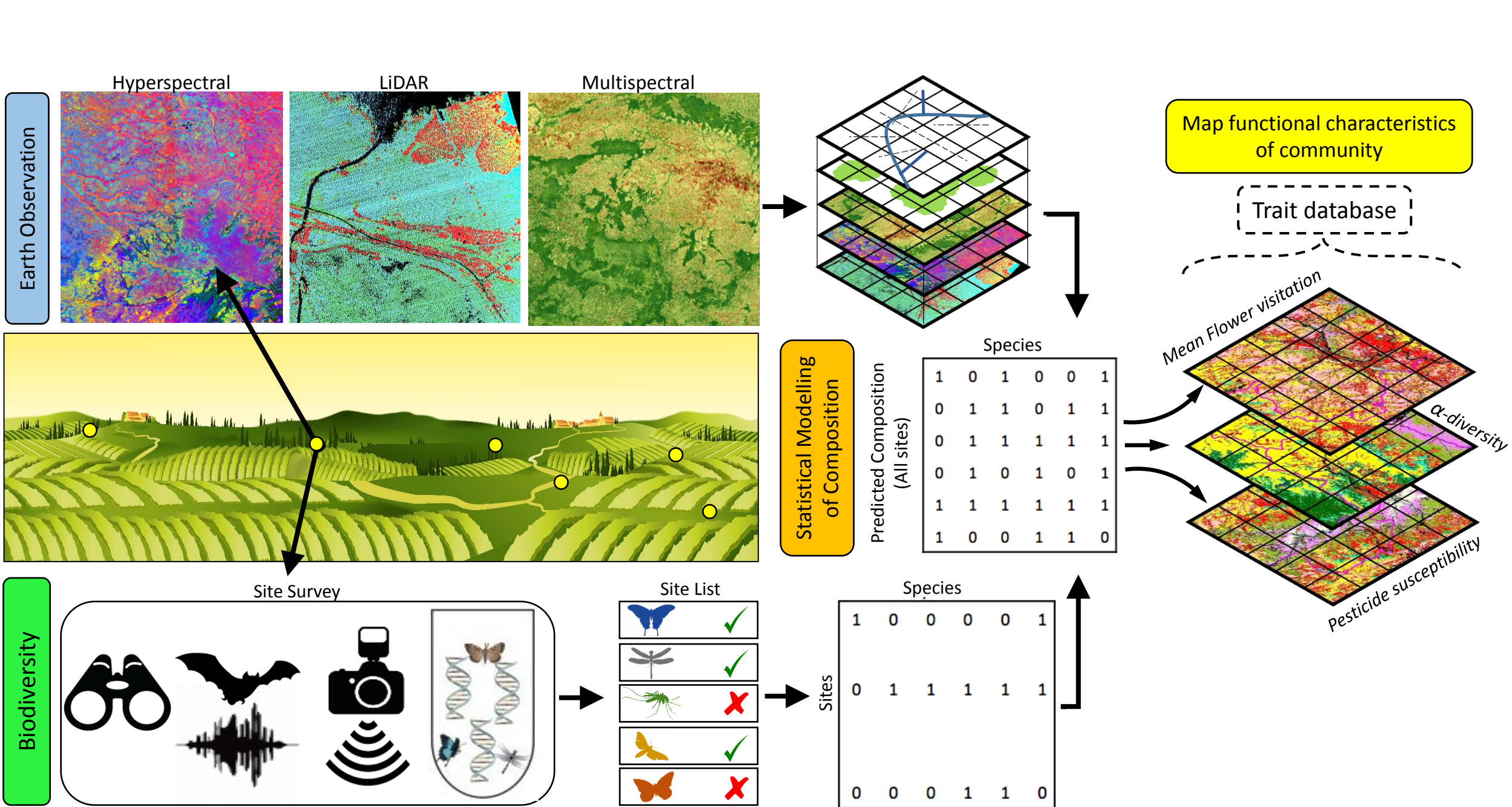
800 **row left:** EO data and other geographical datasets are used to generate spatially
801 continuous maps of biophysical data (**S1, S2**). **Middle row left:** A real landscape with
802 point-sample locations indicated by yellow dots. **Bottom row left:** Biodiversity is
803 recorded manually using traditional methods, automated audio or image recording
804 devices, or metabarcoding or metagenomic pipelines to generate a site X species table
805 (**Figure 2, S3**). However, most of the landscape is not sampled (empty rows in the table).
806 **Right side:** The point samples are combined statistically with continuous biophysical
807 maps to predict biodiversity composition over the whole landscape (**S4**). In combination
808 with ancillary data like trait databases, process-based models can then identify the
809 functional composition of any location and map the expected distributions of ecosystem
810 functions and services.

811 **Figure 2. Metabarcoding and metagenomic processing pipelines for high-throughput**

812 **biodiversity surveys. Top row:** Point locations across a landscape are sampled for
813 biodiversity, and DNA is separately extracted from each sample. Three common sample
814 types are (i) bulk samples of arthropods (depicted here), (ii) environmental DNA (eDNA)

815 from soil, water, and air, and (iii) invertebrate collectors of vertebrate DNA (iDNA), such
816 as mosquitoes, leeches, flies, dung beetles, and ticks. **Left column:** Metabarcoding –
817 Each sample's DNA is amplified via PCR (polymerase chain reaction) for a particular
818 marker gene that is taxonomically informative, the samples are pooled and sequenced
819 on a high-throughput sequencer, and then sorted back to sample by the sample-specific
820 tags added during PCR. The sequences are then clustered into Operational Taxonomic
821 Units (OTUs), which are species hypotheses, and assigned taxonomies by matching
822 against online databases. **Right column:** Meta/mitogenomics – Each sample's total DNA
823 is sequenced, and the output DNA reads are matched to reference genomes, which are
824 often mitochondrial genomes. **Bottom row:** The output of both processing pipelines is a
825 'sample X species' table. Metabarcoding pipelines are useful for general biodiversity
826 discovery and surveys because online barcode databases are more taxonomically
827 complete, and even without taxonomic assignment, it is possible to calculate community
828 metrics from OTUs only. Metagenomic pipelines are more costly, but advantageous when
829 it is important to reliably identify particular sets of species and to a greater extent
830 preserve relative biomass information. See **S3** for further details. Clip-art courtesy of the
831 Integration and Application Network, University of Maryland Center for Environmental
832 Science (ian.umces.edu/symbols/).

833 **Figure 3. Three statistical pathways to map community composition and summary**
834 **metrics from the combination of biodiversity point samples and continuous Earth**
835 **Observation (EO) maps.** Local diversity – α , species turnover – β , and regional diversity –
836 γ . For clarity, the figure only considers models for species occurrence (OCC), not
837 abundance. GAM: Generalised Additive Model. DynamicFOAM is described in Ref. 76.
838 See **S4** for further details.



Site List

	✓
	✓
	✗
	✓
	✗

Sites

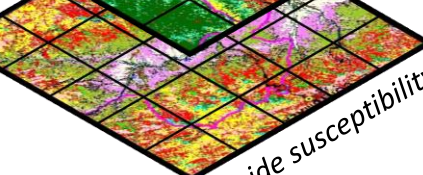
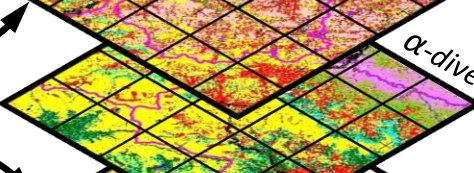
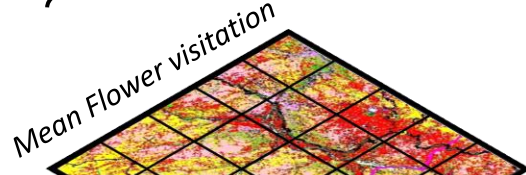
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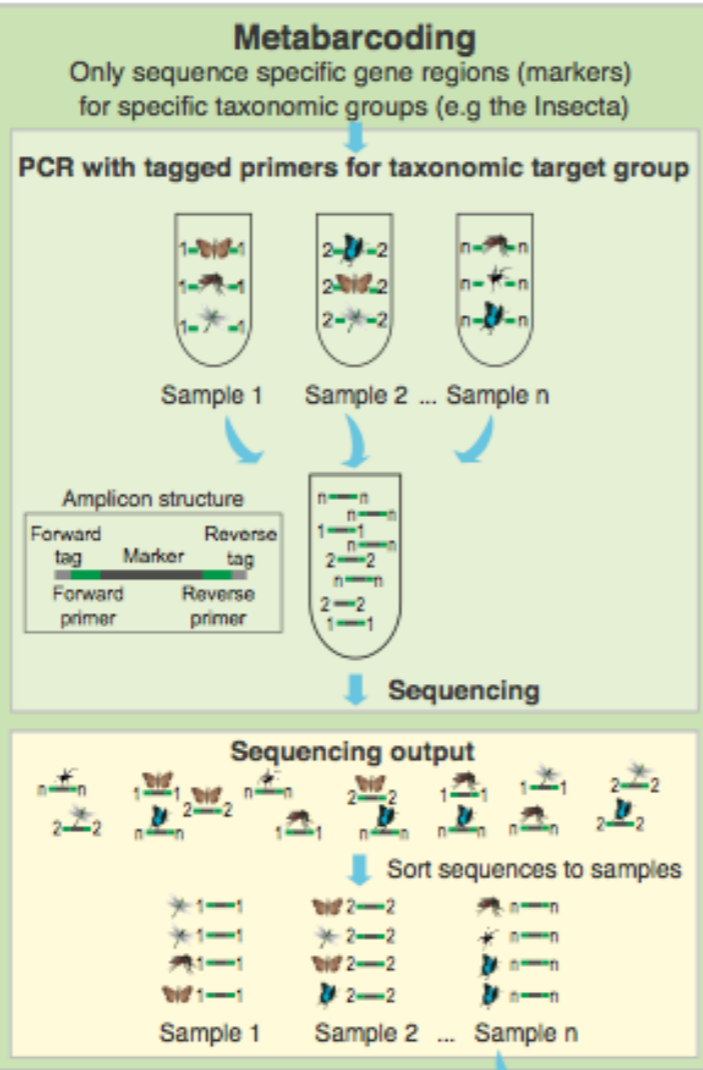
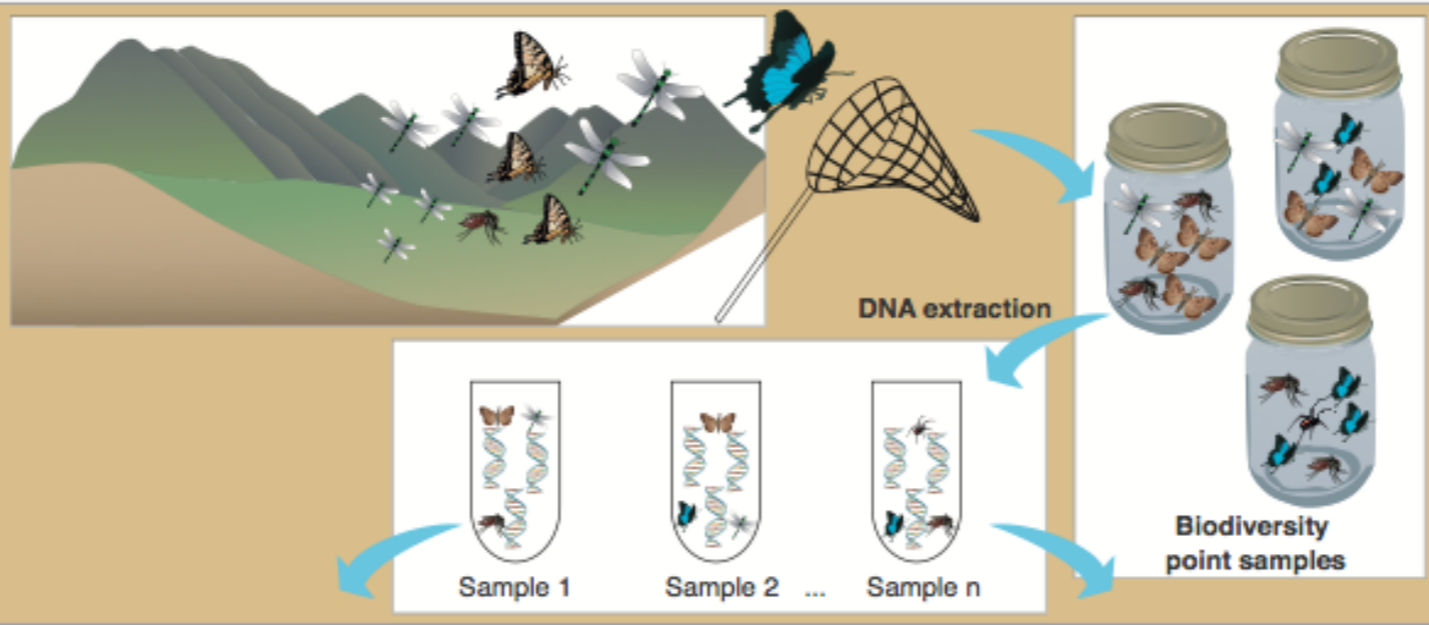
Predicted Composition (All sites)

Species					
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0	1	1	1	1	1
0	1	0	1	0	1
1	1	1	1	1	1
1	0	0	1	1	0

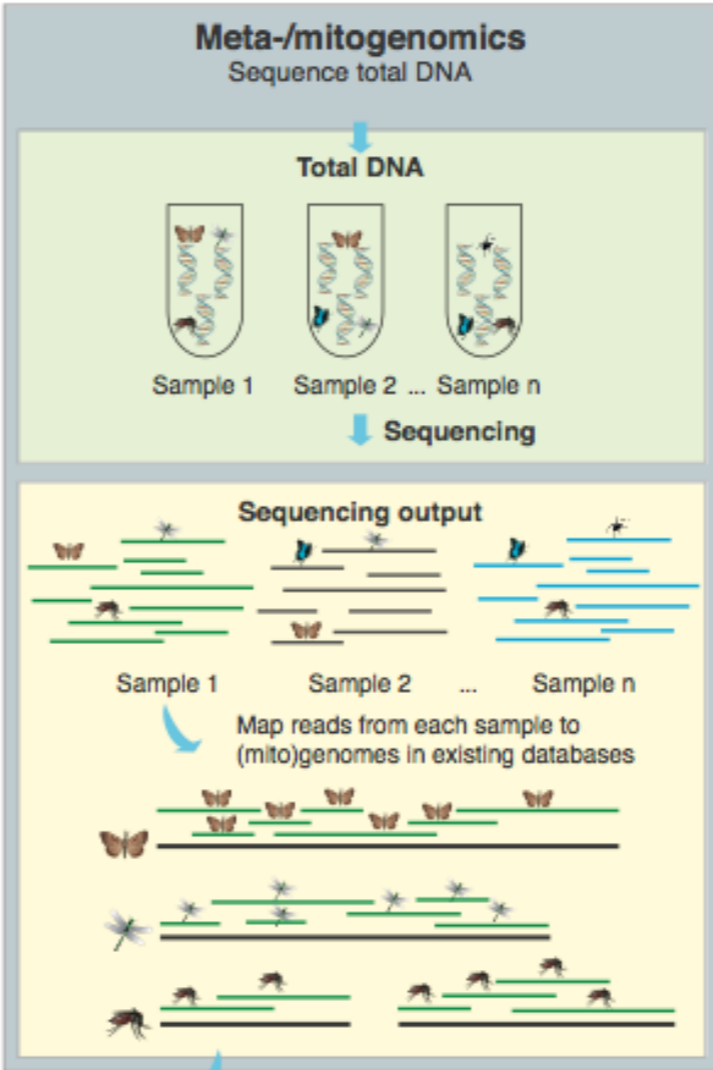
Map functional characteristics of community

Trait database





Metabarcoding is a targeted and cost-effective approach in which only short marker(s) for the taxonomic groups desired for a given biodiversity assessment are sequenced. It is more likely to detect low-biomass taxa than is mito-/metagenomics. Metabarcoding exploits existing reference databases, which are larger than reference database collections for whole (mito)genomes.



Meta-/mitogenomics requires deeper sequencing than metabarcoding because total DNA is sequenced, and only a small fraction of the sequencing output is used for detecting species. Meta-/mitogenomics relies on whole (mito-)genome reference databases, but when these are available, it has higher certainty of taxonomic assignment than does metabarcoding.

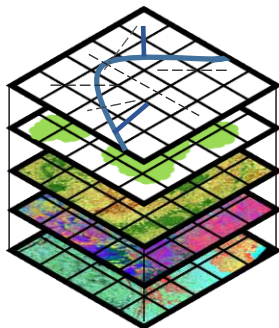
Sample	Species										
	0	1	0	1	0	0	1	0	1	1	0
	1	0	0	0	0	1	0	0	0	0	0
	1	0	1	0	1	1	1	1	0	1	1
	0	1	0	0	0	0	0	0	1	0	0
	1	1	0	1	1	1	1	1	1	0	1
	0	0	0	1	0	1	0	1	1	0	0
	1	0	0	0	0	1	1	0	0	0	0

Joint Species Distribution Models / Latent Variable Models

Biodiversity point samples

EO Spatial covariates

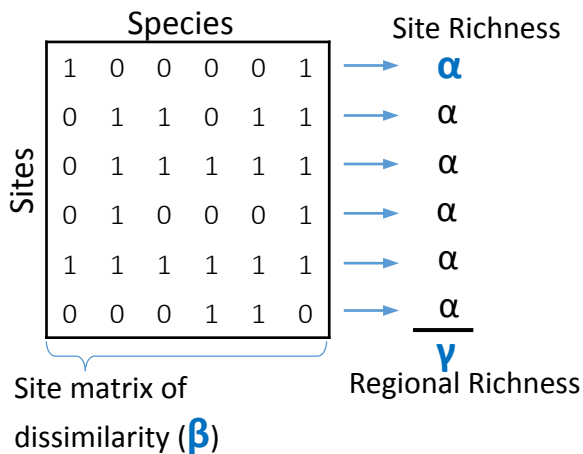
	Species					
Sites	1	0	0	0	0	1
	0	1	1	1	1	1
	0	1	0	0	0	1
	0	0	0	1	1	0



$$OCC = f(\text{Site covariates}) + f(\text{Latent Variables})$$

Species distributions are described as a function of unobserved latent factors as well as observed covariates. Account for species covariance, but do not easily account for differences in species detection.

Predicted probabilities of species occurrences at all sites

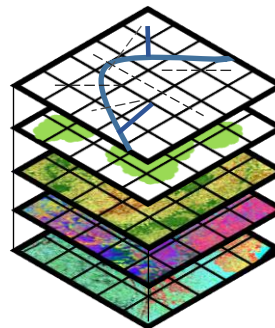


Occupancy-Detection Models

Biodiversity point samples with repeated surveys

EO Spatial covariates

	Species					
Sites	1	0	0	0	0	1
	0	1	1	1	1	1
	0	1	0	0	0	1
	0	0	0	1	1	0



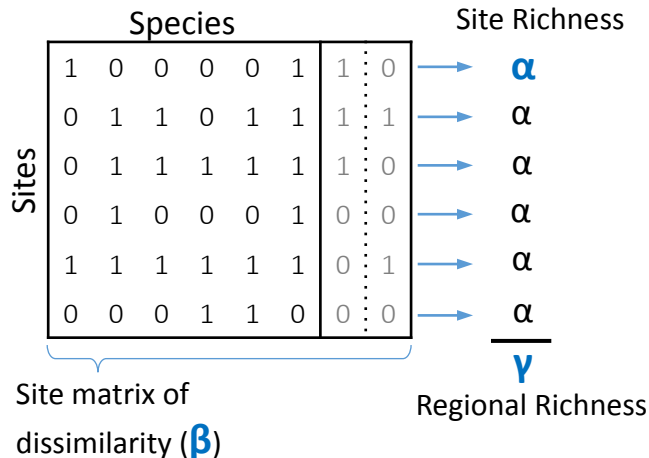
Site covariates

Survey covariates

$$OCC = \text{Occupancy.model} * \text{Detection.model}$$

Environmental covariates can describe both a species' distribution and how that distribution is observed, which itself can depend upon survey characteristics. Account for imperfect detection, but treat species independently.

Predicted probability of species occurrence at all sites (including unobserved species)

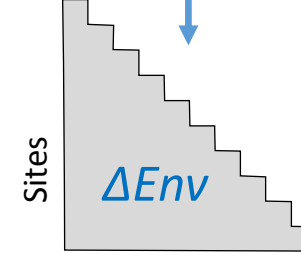
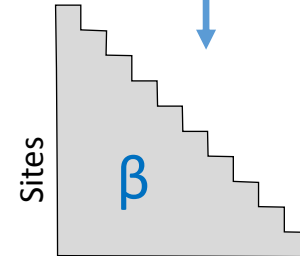
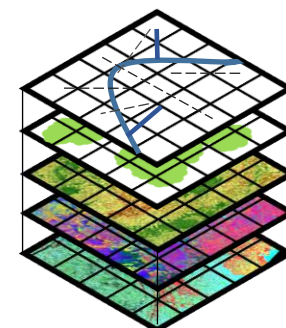


Generalised Dissimilarity Models

Biodiversity point samples (high species diversity)

EO Spatial covariates

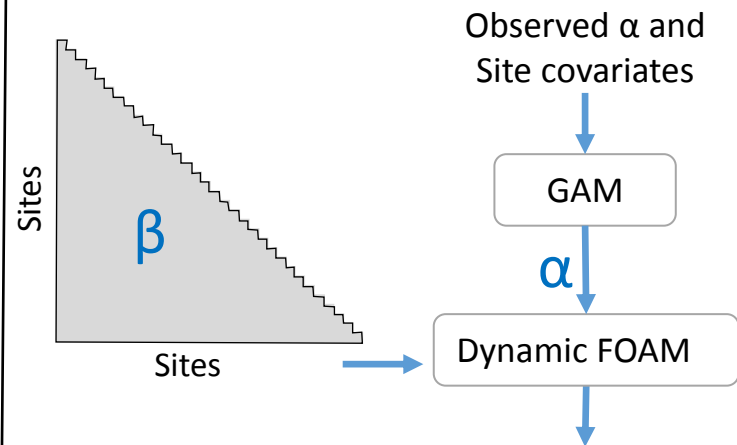
	Species									
Sites	1	0	0	0	0	1	0	0	1	0
	1	1	0	1	1	1	0	1	0	0
	0	0	0	0	1	1	0	0	0	1
	0	1	0	0	0	0	1	0	1	0
	1	1	0	0	0	1	0	0	0	0
	0	1	1	1	0	1	0	0	0	0



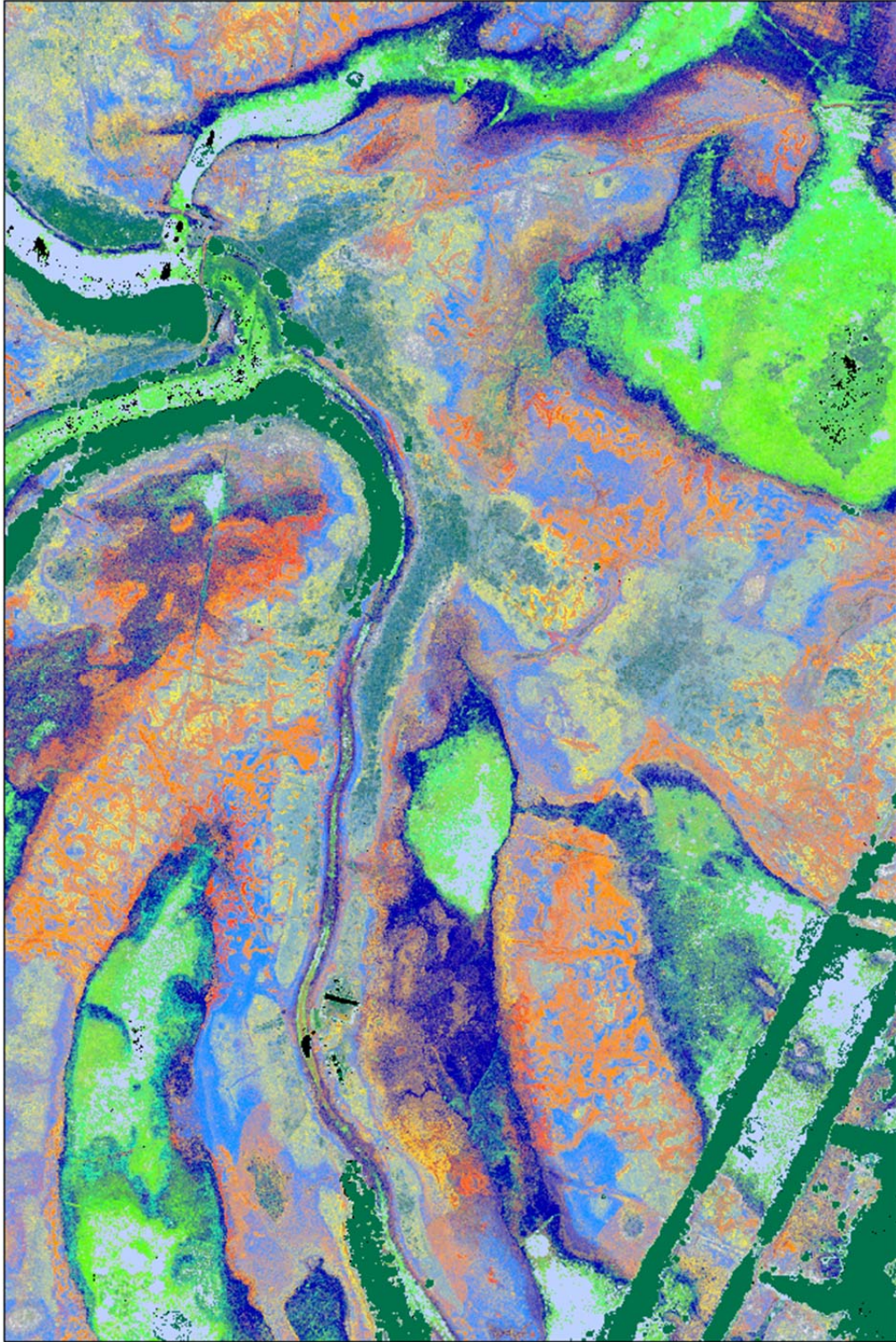
$$\beta_{ij} = f(|Env_i - Env_j|)$$

Compositional dissimilarity (β) between each pair of sites (i and j) is a function of the difference in environmental conditions (ΔEnv).

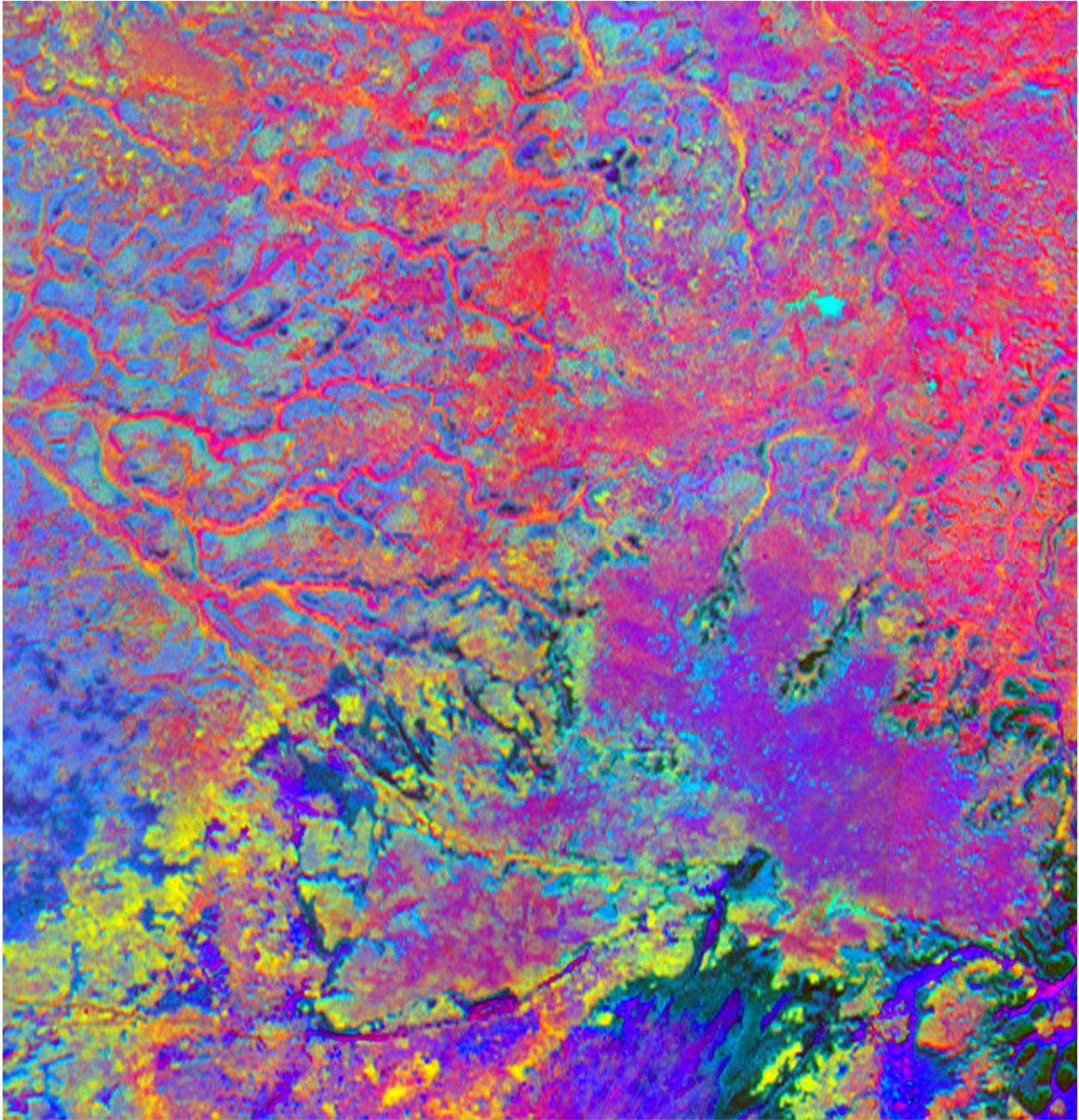
Predicted compositional dissimilarity between any pair of sites (β)



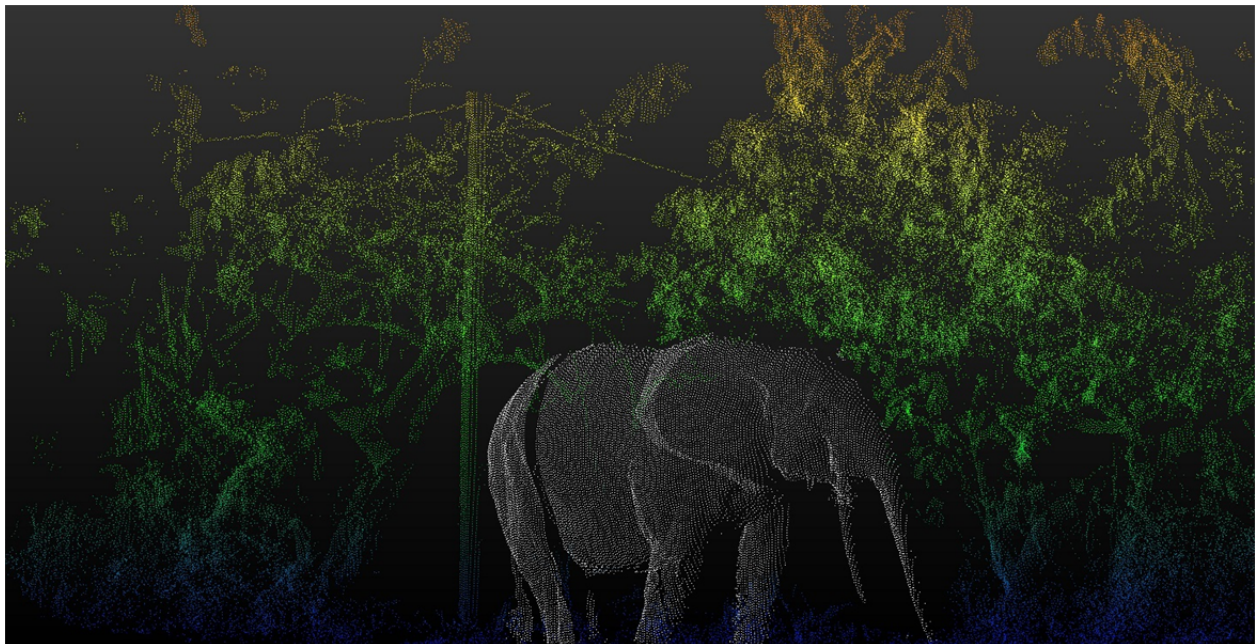
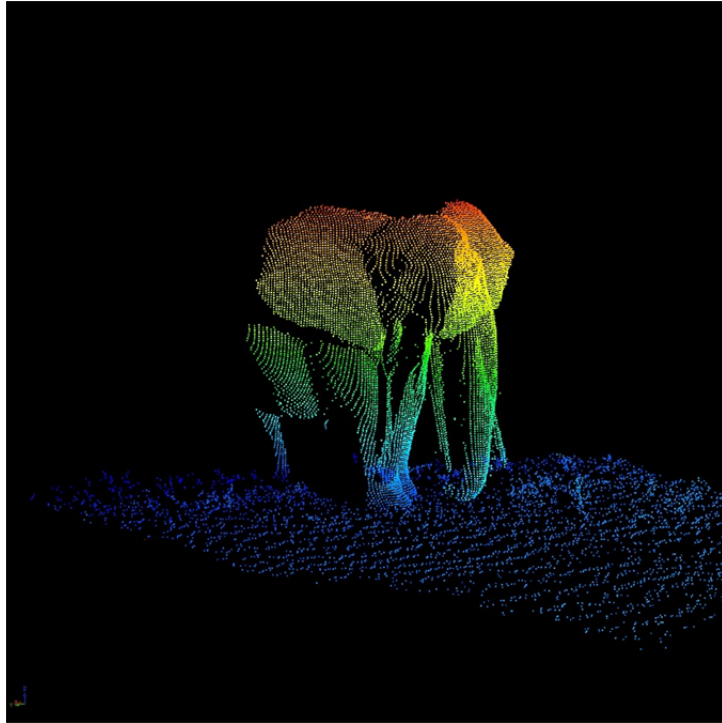
Predicted composition of all sites consistent with patterns of α and β



Fuzzy classification of grassland vegetation in an alkaline grassland in Püspökladány, Hungary, based on airborne LIDAR. Colours represent the weighted probability for a given vegetation class in each cell (0.5m²) (photo credit: András Zlinszky).



Vegetation composition of a peatland using Partial Least Square Regression models on a hyperspectral image. The image is a false colour composite showing the predicted abundance of Graminoids (Red), Shrubs (Green), and Bryophytes (Blue) (photo credit: Beth Cole).



A forest elephant “scanned” during a terrestrial laser-based measurement of a tropical rainforest in Gabon 2013 (photo credit: Kim Calders).

1 Connecting Earth Observation to High-Throughput

2 Biodiversity Data: Supplementary Information

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50 **Supplementary Note 1. Earth Observation Technology**

51 Earth Observation (EO) sensors can be differentiated into active and passive types. Active

52 sensors direct their own source of electromagnetic radiation at the Earth and receive the

53 signal reflected back from the target (e.g. Synthetic Aperture Radar, SAR, transmits

54 microwave pulses). Passive sensors rely on external radiation sources such as the Sun

55 (optical and thermal sensors fall into this category). Different sensors record

56 electromagnetic radiation in specific ranges of the electromagnetic spectrum, with
57 wavelengths from 400-700 nm (visible light) to 700-2400 nm (near to shortwave infrared),
58 3000-14000 nm (thermally emitted radiation), and 1 cm-1 m (microwave radar wavelengths).
59 Passive EO instruments record radiances at sensor, which generally have to be corrected
60 for atmospheric aerosol and water vapour impacts in order to estimate the land surface
61 reflectances from which EO-derived metrics are usually extracted. Active radar sensors
62 record the transmitted energy that is scattered back from the surface, and since
63 microwaves penetrate clouds, they provide an all-weather observing capability. However,
64 longer wavelengths such as L-band (15-30 cm) and P-band (30-100 cm) can be affected by
65 fluctuations in the total electron content of the ionosphere and the Faraday rotation. Optical
66 and radar sensors are available from both airborne platforms (drones, aircraft) and
67 spaceborne platforms (polar orbiting and geostationary satellites, international space
68 station). Important characteristics of an EO sensor are its spectral coverage and spectral
69 resolution (which bands of the electromagnetic spectrum it measures and at what
70 wavelength detail), its spatial resolution (pixel size), and temporal repeat-frequency (number
71 of days between two acquisitions at the same location). Many applications do not require
72 frequent acquisitions, but multiple images can for instance help account for artefacts and
73 error due to cloud cover¹.

74 Light Detection and Ranging (LiDAR) is an active remote-sensing technique that transmits
75 infrared or visible polarised light and records the intensity and temporal delay of the
76 received signal. Because of the constant speed of light in air, airborne LiDAR can measure
77 the vertical height of objects with very high accuracy². Radar interferometry from tandem
78 satellite constellations can also measure vertical height but is not as accurate as LiDAR and
79 has a coarser spatial resolution than airborne LiDAR³. LiDAR systems can be imaging
80 LiDARs or profiling LiDARs, and some systems record the full waveform of the received
81 radiation, allowing the study of vegetation canopies in great detail, while others only record

82 the first and last return of the waveform. LiDAR instruments are usually mounted on
83 airborne platforms (aircraft, drones) or used as terrestrial instruments (mounted on a tripod
84 or used as a handheld device), with the exception of the spaceborne ICESAT-GLAS
85 profiling LiDAR and the planned GEDI mission to be mounted on the International Space
86 Station.

87 **Supplementary Note 2. Biodiversity and ecosystem information in** 88 **EO data**

89 The spatial and temporal coverage of EO cannot be matched by *in-situ* surveys, and
90 mapping of habitat extent and land cover types has therefore been incorporated into
91 national EO-monitoring programs for many years^{4,5}.

92 *Aboveground biomass and carbon storage* – Forest ecosystems play a crucial role in global
93 biogeochemical cycles, and deforestation has been a major contributing factor to
94 increasing anthropogenic carbon emissions. Global initiatives such as REDD+ (Reducing
95 emissions from deforestation and forest degradation, and the role of conservation,
96 sustainable management of forests and enhancement of forest carbon stocks in developing
97 countries) has been negotiated by the UNFCCC for years and was reiterated in the Paris
98 Agreement⁶. While the main aim is to mitigate climate change by reducing carbon
99 emissions, for which developing countries receive results-based payments, safeguards and
100 non-carbon benefits (NCBs) are recognised, including consistency with the conservation of
101 natural forests and biodiversity^{7,8}. The success of REDD+ therefore depends on our ability
102 to accurately quantify the global distribution of carbon sources and sinks, for which EO
103 such as SAR or LiDAR are now being developed⁹.

104 Airborne LiDAR can quantify forest canopy height and complexity, and understory density
105 over large areas, and has been particularly useful in forestry¹⁰. Although individual trees can

106 be mapped by very high pulse densities¹¹, forest structure is more commonly described by
107 the heights of a lower density point-cloud aggregated over a forest plot. The average
108 parameters for that forest can then be used to estimate aboveground biomass, which can
109 be translated to ecosystem services like carbon sequestration and storage¹². Hollaus *et al.*¹³
110 demonstrated that even simple models could make accurate predictions of timber stock in
111 alpine forests after being calibrated with inventory plot data ($r^2 > 0.80$). The study also
112 showed model accuracy was not sensitive to LiDAR point density or the season of
113 acquisition.

114 Although performance is likely to vary among habitat types, with accuracy usually greater in
115 low diversity systems, and dependent on the number and size of calibration plots, a meta-
116 analysis of more than 70 studies by Zolkos *et al.*¹⁴ found airborne LiDAR to be more
117 accurate than radar or passive optical data. Yet more accurate estimates of carbon stocks
118 may be possible using hyperspectral to discriminate tree species¹⁵. LiDAR can also be used
119 in ecosystems other than forests. For example, Zlinsky *et al.*¹⁶ demonstrated that LiDAR can
120 replicate ground-based multi-parameter assessments of habitat conservation status in a
121 Natura 2000 grassland reserve in Hungary (Overall Accuracy=0.8); and using EO, the entire
122 reserve could be surveyed.

123 *Biodiversity* – While the main focus of REDD+ is to reduce carbon emissions, there is also
124 great potential to improve predictions of spatial patterns of biodiversity from vegetation
125 structure. As argued elsewhere in this paper, these relationships could prove critical to
126 achieving the ambitions of initiatives like REDD+ without compromising the benefits for
127 biodiversity conservation¹⁷.

128 For instance, early EO products like NDVI (normalised difference vegetation index) have
129 been shown to approximate changes in vegetation structure and hence turnover of the
130 invertebrate ground fauna^{18,19}, and more recently high spatial resolution airborne imagery

131 has been shown to identify canopy gaps that are associated with the diversity of
132 understorey vegetation²⁰. Spectral traits of plants are determined by their physiological and
133 morphological traits, and there are demonstrated applications using EO to reveal the
134 distribution of vegetation types^{21,22}, functional types²³, richness²⁴, and temporal changes²⁵ to
135 name but a few²⁶. Nonetheless, the success of habitat mapping varies with habitat type,
136 and research into the right combination of sensors and algorithms is ongoing²⁷⁻²⁹. Finally,
137 the combination of hyperspectral sensors and LiDAR provides an extremely detailed picture
138 of the Earth's surface, potentially capable of identifying the composition of individual trees
139 in some landscapes³⁰ and reproducing patterns of tree richness and turnover in highly
140 diverse rainforests at landscape scales^{22,31,32}. Eventually, similar measurements that directly
141 observe or predict the distribution of biodiversity could be extended globally as satellite-
142 based LiDAR and hyperspectral imaging systems become operational (**S1**).

143 LiDAR-derived structural metrics have also proven useful as predictors in many *animal*
144 groups^{33,34}, and LiDAR could be more cost-effective than traditional methods for censusing
145 invertebrate communities³⁵ and is likely to perform even better once taxonomic
146 uncertainties are reduced with DNA-based identification³⁶.

147 **Supplementary Note 3. Biodiversity technology**

148 **Automated Recording Devices (ARDs)**

149 The first set of technologies encompass ARDs, such as camera traps and bioacoustic
150 recorders that can be left in even remote field locations for weeks to months, capturing
151 records of birds, amphibians, and mammals, and thus allowing continuous sampling of tens
152 of thousands of hectares at a time, with occasional fieldwork to maintain sensors and
153 retrieve data.

154 *Camera traps.* - Camera traps are powerful tools for detecting medium to larger-sized
155 mammal species, particularly in forests³⁷, and they have also been used to study ground-
156 dwelling bird species^{38,39} and lizards⁴⁰. Camera traps readily detect rare and cryptic or
157 nocturnal species, and once set up, operate independently of an observer until battery life
158 or memory capacity is exhausted. Early models used film roll cameras and active sensors,
159 where an infrared beam was established across a potential animal path, and the unit was
160 triggered when that beam was broken. Set-up of the infrared beam (height, positioning) had
161 to be tailored specifically to the target species, and early studies often focused on the
162 demography of single charismatic species such as tigers^{41,42}. Even with passive heat-in-
163 motion sensors, which made for a more flexible set-up because of the increased area over
164 which animals can be detected, the low number of exposures on film rolls was a severely
165 limiting factor to the time that camera traps could be left in the field without revisiting.

166 The development of a wide range of digital models in the last 10 years has greatly
167 expanded the applications of camera traps. With increasingly capacious memory cards and
168 batteries, cameras can now routinely be left unattended for weeks up to several months
169 (depending on the expected amount of animal traffic). Options for infrared flash make the
170 equipment nearly invisible, even at night, reducing theft. Modern camera traps capture
171 images of sufficient quality to allow identification to species in 80-90% of photos. Rapid
172 sequential triggers of video options further increase the likelihood of obtaining the footage
173 needed to identify species and individuals. Whereas the up-front investment in the
174 equipment can be high (depending on manufacturer and specifications, a single trap can
175 cost anywhere between \$80 and \$800), camera traps have repeatedly been shown to beat
176 other methods (e.g. transects, track plates) in their efficiency to document medium to large
177 terrestrial mammal species⁴³⁻⁴⁵, and they become more cost effective for longer surveys⁴⁴.

178 Although the method is still used to study the demography of individual species, particularly
179 those with natural coat patterns allowing individual identification⁴⁶⁻⁴⁸, camera traps are now

180 also used in behavioural studies⁴⁹ and to study species interactions in space and time^{50,51}.
181 Moreover, camera traps are increasingly used to survey terrestrial⁵²⁻⁵⁴ and even arboreal
182 mammal communities⁵⁵⁻⁵⁷. Camera traps have been proposed as a tool in systematic
183 biodiversity assessments in the context of biodiversity co-benefits of forest management
184 certification and REDD+ payments⁵⁸. As an example application, a recent study on
185 mammalian communities in Bornean forest reserves revealed that particularly threatened
186 species benefit from sustainable forest management practices, applied in the context of
187 certification by the Forest Stewardship Council (FSC)⁵⁴. Similarly, such standardised
188 camera-trapping surveys, if repeated over time, can be used to monitor population and
189 biodiversity trends, which would be impossible using traditional, observer-based fieldwork
190 techniques.

191 How readily camera traps detect certain species is a function of many factors, including the
192 species' behaviour and abundance, and the specific location and setup of the camera
193 traps^{59,60}. For example, arboreal species are harder to detect with ground-based cameras
194 than terrestrial species, and if cameras are set up preferably along roads and trails, species
195 that use these trails will be detected sooner and more frequently than species that prefer to
196 move through vegetation. Comparing biodiversity inventory data across sites and/or years
197 therefore requires a standardised study design, and application of analytical methods that
198 account for these differences in detectability (see Occupancy Modelling, below).

199 *Bioacoustic sensors.* - Species that produce acoustic signals can further be surveyed with
200 standalone bioacoustic sensors⁶¹. Taxonomic groups most frequently studied with
201 bioacoustic methods include birds^{62,63}, bats^{64,65}, anurans⁶³, certain insects^{66,67}, and
202 cetaceans⁶⁸. Bioacoustic recordings have also been used to study fish⁶⁹, and non-flying
203 mammals such as forest elephants⁷⁰ and primates^{71,72}. Using calls to detect and identify
204 species has a long standing history in bird studies⁷³. Handheld sound recorders are a useful
205 tool in such surveys to create permanent records of species audio-detections and to allow

206 for later identification (or verification) of records by specialists. There also exist standalone
207 bioacoustic sensors⁷⁴ that, similar to camera traps, can be set up in the field to collect
208 audio information without an observer's presence. Also similar to camera traps, they are
209 primarily limited by battery and storage capacity, and storage capacity has increased
210 dramatically with the switch from analogue to digital equipment⁶³. Automatic digital
211 recording systems can be programmed to record continuously or at certain times, or,
212 alternatively, more advanced equipment can be triggered by calls above a certain
213 amplitude or of a certain frequency spectrum^{75,76}.

214 Once recorded, calls/songs can be identified directly by a trained human observer (but of
215 course only if the species produces a sound that is audible to humans) and/or by
216 visualisation. The latter depicts species-specific acoustic parameters such as the temporal
217 structure and frequency composition of a call/song. Most frequently, visualisation takes the
218 form of a spectrogram, which shows the evolution of the frequency structure of a call over
219 time, using color-coding for changes in amplitude⁷⁵. Such visualisation can reveal call
220 characteristics that the human ear might not perceive. Call-matching to species based on
221 these characteristics can be performed manually, or using computer algorithms. Obrist *et*
222 *al.*⁷⁵ report that most automated identification software packages achieve a 90%
223 recognition rate but can rarely be expected to cover all species present in a sample.
224 Conversely, Russo and Voigt⁶⁵ have voiced concern over the accuracy of automated
225 species identification of bat calls.

226 Criticism notwithstanding, advances in the development of audio-recorders and call-
227 matching software make automated devices a promising tool for biodiversity inventory and
228 monitoring⁵⁸. Such surveys, however, require extensive preliminary studies to compile
229 reference call data bases. Similar to genetic reference libraries, there are now multiple
230 available sound libraries (e.g. <http://www.ibac.info/links.html#libs>, accessed 8 Dec 2016),
231 but especially for species-rich tropical communities, bioacoustic databases are currently

232 limited⁷⁷. Circumventing the need for species identification, some studies have suggested
233 the use of bioacoustic diversity as a measure in and of itself. Rather than identifying
234 individual calls and species, this approach is based on measuring the acoustic entropy (i.e.
235 temporal and frequency heterogeneity) of entire soundscapes, and, on the assumption that
236 there is competition for sound niches in time and frequency, a more complex soundscape
237 is taken as an index for a more diverse community⁷⁸. Such bioacoustics diversity indices
238 have been shown to correlate with taxonomic and functional diversity in birds⁷⁹ and are a
239 promising field of study, albeit in need of further development and testing⁸⁰.

240 As with other survey methods, detectability and identifiability of individuals and species can
241 be influenced by their vocalisation and other behaviour, habitat, weather, time of day, or the
242 sensitivity of the recording equipment. For example, wind and concurrent vocalisation by
243 other species were found to have a negative impact on the ability to identify frog calls⁸¹, and
244 different equipment has been shown to result in different numbers of bird species
245 detected⁸². In addition to false negatives (i.e. failing to record a species even though it is
246 present), misidentification of calls can result in false positives⁸³. As such, standardised
247 surveys and appropriate analytical methods are required to ensure comparability of results
248 across space and time. Occupancy models, for example (discussed below) were developed
249 to account for false negatives and can be adjusted to account for false positives as well^{84,85}.
250 They have been successfully used in combination with automated acoustic monitoring⁸⁶.

251 **DNA-based methods**

252 Almost all DNA-based techniques exploit the stylised fact that some DNA regions exhibit
253 higher levels of sequence difference between species and low levels of difference within
254 species, which can be used to tell species apart. For animals, the best known of these so-
255 called 'DNA barcodes' is a 658-nucleotide portion of the mitochondrial cytochrome oxidase
256 subunit I gene, or COI, which taxonomists have used to build an online reference database

257 that links sequences to species (boldsystems.org, accessed 11 Oct 2016)⁸⁷. Other
258 mitochondrial markers can also be used for taxonomic assignment, and these are available
259 in online databases such as GenBank (blast.ncbi.nlm.nih.gov, accessed 11 Oct 2016). An
260 organism can thus be assigned a taxonomic identification by extracting its DNA, amplifying
261 it with a primer set for the chosen marker(s), sequencing these, and comparing them to a
262 DNA reference database. Even if a species is not represented in a database, its congeners
263 or confamilials usually are, allowing at least higher-level taxonomic identification.

264 When going from DNA barcoding of single specimens, as described above, to using DNA in
265 synoptic biodiversity surveys, the major challenge is the need to assign taxonomic names
266 to mixed samples containing DNA from multiple taxa, such as occurs in soil, water, faeces,
267 and bulk insect samples. The rise of high-throughput sequencing platforms now makes this
268 routine, and three major approaches are now being used: metabarcoding, high-throughput
269 individual barcoding, and meta/mitogenomics.

270 *Metabarcoding.* – DNA is extracted from bulk or environmental samples containing DNA
271 from a mix of different taxa, and a taxonomically informative marker like COI is PCR
272 amplified using a universal primer set targeting the taxonomic group of interest (**Fig. 2** Main
273 Text). In this way, only DNA markers of interest are sequenced, making this a cost-effective
274 approach. The resulting sequences are then clustered into self-similar sets of sequences,
275 each known as an Operational Taxonomic Unit (OTU), which is a species hypothesis. A
276 representative sequence is taken from each OTU and assigned a taxonomy using an online
277 database. The main output of metabarcoding is the classic ecological table of sample X
278 species (OTU), but now achievable for at least hundreds of species across hundreds of
279 samples, plus, to a lesser extent, their phylogenetic relationships. Metabarcoding data thus
280 carry information on species co-occurrence at an unprecedented scale for joint-species-
281 distribution modelling.

282 Metabarcoding relieves the taxonomic bottleneck, and it also helps relieve the sampling
283 bottleneck. Firstly, metabarcoding can be applied to taxa such as meiofauna and dipterans
284 that are easy to collect and ecologically informative but are so difficult to identify
285 morphologically that they have been ignored in conventional surveys. Secondly,
286 metabarcoding allows difficult-to-find species, such as fungi, fish, and terrestrial
287 vertebrates, to be detected directly from microscopic bits of tissue that can be filtered out
288 of soil, water, air, and parasites, known as 'environmental DNA' or eDNA^{88,89}. For instance,
289 leeches, flies, mosquitoes, dung beetles, and ticks retain trace amounts of DNA from their
290 previous meals on animal hosts or faeces, so mass invertebrate trapping could be used to
291 survey other wildlife⁹⁰.

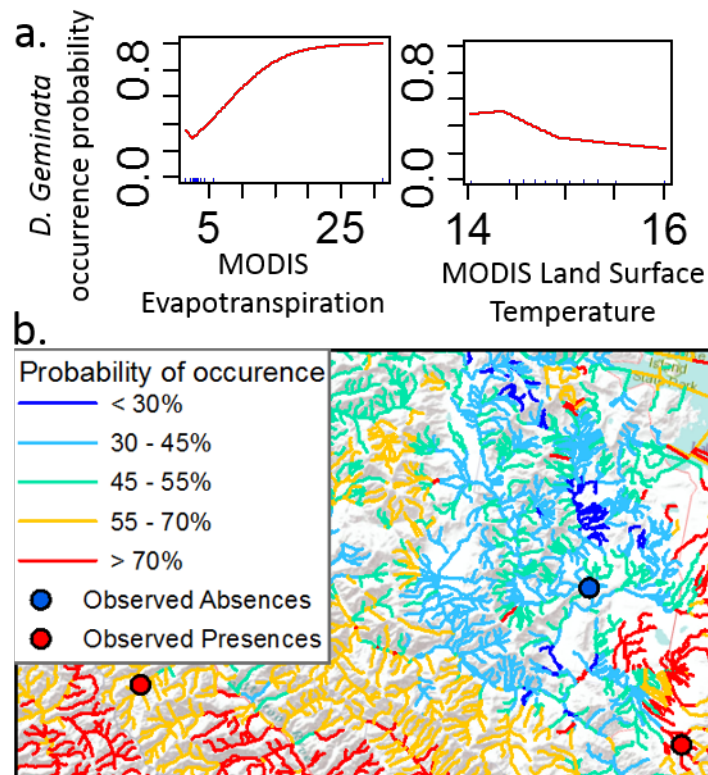
292 However, metabarcoding unavoidably introduces error, including *inter alia* taxonomic
293 uncertainty due to e.g. PCR and sequencing error and incomplete reference databases,
294 sample cross-contamination, and loss of species, biomass, and abundance information.
295 Judicious sampling and primer design, lab practice, and bioinformatic and statistical
296 pipelines are able to correct or compensate for these errors, and studies have shown that
297 metabarcoding datasets reflect on-the-ground reality sufficiently closely to allow correct
298 management decisions⁹¹⁻⁹⁶. It is worth noting that errors are explicit and quantifiable in
299 DNA-based pipelines, whereas conventional surveys contain important error sources, such
300 as visual misidentifications⁹⁷, that are essentially impossible to quantify or correct
301 retrospectively.

302 *High-throughput individual barcoding* – In this method⁹⁸, large numbers of organisms,
303 typically insects, are *individually* extracted, amplified, and tagged during amplification.
304 Hundreds of individual amplicons are then pooled and sequenced, producing a separate
305 barcode for each organism. Throughput is lower and workload is higher than in
306 metabarcoding, but abundance information is preserved, and individual organisms can be
307 revisited for further taxonomic study.

308 *Meta/mitogenomics* – Like metabarcoding, metagenomics can be used on bulk or
309 environmental samples, but instead of targeting a specific gene, all DNA is sequenced, and
310 the output datasets are interrogated *in silico* for taxonomically and functionally informative
311 gene sequences (**Fig. 2** Main Text). Compared to metabarcoding, the advantage of this
312 genomic approach is that it does not require a PCR amplification step to enrich target taxa,
313 which should reduce bias. If samples are sequenced deeply enough, even low-biomass
314 species can be detected in the mix (although sequencer library construction still imposes
315 some biases). Metagenomics also preserves more information on species relative
316 biomasses (a proxy for ecosystem-function importance), can reduce the risk of sample
317 contamination, and depending on the number of samples, can reduce workload. Lastly, it
318 increases the certainty of taxonomic assignment for species that are present in reference
319 database. Currently, metagenomics is routinely applied to microbial communities but is not
320 yet applied to Eukaryotes, due to their much larger genomes and thus higher costs.
321 However, bioinformatic approaches that allow rapid pairwise comparisons of genomic
322 datasets⁹⁹ and continued decreases in sequencing costs will make this approach feasible
323 for Eukaryotes. That said, because orders-of-magnitude fewer species have been genome-
324 sequenced, relative to barcode databases, metagenomics applied to Eukaryotes is best
325 suited for studies that focus on hundreds of target species or fewer, for which it is possible
326 to build custom reference databases.

327 In mitogenomics, the focus is on mitochondrial genomes, which can be individually
328 assembled out of low-coverage sequencing of bulk samples ('genome skims'), even though
329 mitochondrial reads typically make up <1% of a sequencer's output¹⁰⁰. This greatly reduces
330 the cost of building reference databases. Mitogenomics has been used to reconstruct the
331 phylogenetic community structure of soil-dwelling beetle communities¹⁰¹ and to reliably
332 assign bee species to samples, even after the samples had been DNA-cross-contaminated
333 by handling¹⁰².

334 *Single-species detection* – Finally, in situations where it is imperative to detect particular
335 species of concern (e.g. early detection of invasive species or monitoring threatened
336 species) with high probability, older molecular techniques can be used and/or added to the
337 above methods. Species-specific primers can be used in addition to generic primers during
338 metabarcoding to increase detection probability¹⁰³, or species-specific quantitative PCR
339 (qPCR) can be conducted on eDNA samples. Although low throughput, this application of
340 targeted qPCR reduces false negatives, provided that proper lab procedure, including
341 negatives controls, is followed¹⁰⁴. Improved detection rates lead to improvements in model
342 performance, thus increasing the reliability of the predicted distributions of these species of
343 concern, and greater cost efficiency¹⁰⁵. Single-species detections using qPCR have been
344 combined with MODIS satellite observations to build maximum-entropy species distribution
345 models that predicted the distribution of an invasive diatom (*Didymosphenia geminata*)
346 across the Rocky Mountains (Fig S3.1¹⁰⁶). Models based on occurrence data from both
347 eDNA and traditional methods correctly predicted occurrence of *D. geminata* at external
348 validation sites with a 93 – 100% correct classification rate (area under the receiver
349 operating characteristic curve, a combined measure of sensitivity and specificity, ranged
350 from 0.94 to 1.00). Temporally concurrent environmental predictors, including
351 evapotranspiration or land surface temperature data from MODIS, allow these models to
352 account for spatial and temporal variation and produce robust predictions (Fig S3.1a). This
353 provides natural resource managers spatially explicit and extensive predictions on where
354 this invasive species is likely to occur. The same approach is also being applied to mapping
355 distributions of six native fish on the north-slope of Alaska to aid in their conservation¹⁰⁶.



Supplementary Figure 3.1 a: Relationship between MODIS measurements of evapotranspiration and land surface temperature and the occurrence of the invasive diatom *D. geminata*. **b:** Resulting maps of probability of *D. geminata* occurrence from applying model to individual stream segments.

356

357 **Supplementary Note 4. Statistical modelling**

358 *Occupancy Detection Models* – Logistical constraints dictate that a site-by-species matrix
 359 can only ever comprise a finite set of point samples, leaving most of the environment
 360 unsampled. Moreover, even within sampled sites, an unavoidable problem is false
 361 negatives: species that are indeed present but not detected^{107,108}, and in some cases false
 362 positives (species detected that are in fact absent). To correct for imperfect detection,
 363 occupancy-detection models are used to disentangle the factors that determine the
 364 occurrence of a species from those that affect the probability of detection, given
 365 occurrence¹⁰⁹. To estimate the probability of detection, a location is repeatedly sampled,
 366 either by spatially sub-sampling a site, or by re-visiting the same location multiple times

367 within a short time period. A hierarchical generalised linear mixed model (GLMM) –
368 technically a zero-inflated logistic regression of species detection/non-detection data – is
369 then used to predict the probability that a species occurs at a site, based on the site’s
370 environmental covariates and the empirically estimated probability of detection, which can
371 also itself be a function of site- and time-specific covariates.

372 *Community Occupancy Detection Models* – In the simplest application of occupancy
373 detection, each species is considered independent, so a multi-species model simply
374 combines the species’ environmental responses and their different detectabilities, and
375 calculates metrics of diversity either from occupancy probabilities (in a likelihood
376 framework, richness is the sum of all occupancy probabilities at a site), or from realised
377 occupancy states (in a Bayesian framework, richness is the number of species estimated to
378 occur at that site)^{110,111}. However, if the environmental responses of multiple species follow
379 a common distribution, community occupancy detection models allow individual
380 coefficients to be modelled as a random effect, whereby the data-poor species borrow
381 information from data-rich species^{112,113}, which allows information on species traits to be
382 included as predictors¹¹⁴. Furthermore, based on differences in species detection
383 probabilities, occupancy models can also estimate the number of species that were never
384 detected, by introducing zero-inflation within the inputs (“data augmentation”^{115,116}), recently
385 extended for multi-region comparison¹¹⁷. More complex models can include the effect of
386 community dynamics on spatial and temporal variation in occurrence¹¹⁸.

387 *Joint Species Distribution Models / Latent Variable Models* – An extension of the single-
388 species approach is to consider all pairwise co-occurrences among species¹¹⁹. These so-
389 called joint species distribution models (JSDMs) predict multi-species responses by not
390 only modelling species-specific responses to environmental covariates as random effects
391 but also accounting for residual patterns of co-occurrence not explained by environmental
392 factors¹²⁰. In the past, the number of taxa that J-SDMs could consider was limited because

393 the number of parameters in unstructured variance-covariance matrices rises rapidly¹²¹.
394 However, JSDMs can now analyse high numbers of species by inducing correlation among
395 taxa using ‘latent’ unobserved factors¹²⁰. Residual correlation might indicate species
396 interactions, like competition or predation, unmeasured predictors, spatial autocorrelation,
397 or misspecification of the model, all of which warrant further investigation¹²². Spatially
398 explicit latent variables allow one to predict a species community for a focal site using as
399 predictors not only the environmental variables measured at the focal site, but also the
400 occurrences and co-occurrences of the species in nearby sites¹²³, thus providing a
401 statistically efficient tool for producing interpolated species distribution maps from sparse
402 data on species rich communities. In principle, detection probability itself could also be
403 included as a layer describing the observation process¹²⁴⁻¹²⁶. LVMs are currently an area of
404 active research, and there has been rapid progress to expand computational limits and
405 integrate with the breadth of previous development using hierarchical mixed models¹²⁰. Of
406 particular interest is the opportunity to cluster species responses to environmental
407 covariates according to species traits (i.e. “the fourth-corner problem”¹²⁷) making it easier to
408 translate compositional turnover to functional shifts¹²⁸.

409 *Generalised Dissimilarity Models* – Finally, in very diverse communities with hundreds or
410 thousands of taxa (e.g. soil fauna), it might not be meaningful to model the responses of
411 individual species. Instead, generalised dissimilarity models (GDM) use a pairwise matrix of
412 compositional dissimilarity to predict the nonlinear response of compositional turnover to
413 environmental changes; weighting and transforming environmental variables so that
414 conversion of multidimensional environmental space best describes the scaled turnover of
415 biological composition¹²⁹. GDM can help identify new sampling sites for more reliable
416 prediction¹³⁰, and uncertainty in variable selection can be further evaluated using Bayesian
417 bootstrapping¹³¹. The dissimilarity matrix can also be derived from other biological distance
418 metrics like sequence reads, allelic turnover, functional differences, or phylogenetic

419 diversity^{99,132,133}. The link between turnover of composition or function can then be tested
420 using scaled environmental variables as predictors of spatial or temporal changes in service
421 provision¹³⁴.

422 GDM has already been incorporated into EO-based applications to estimate ecological
423 values at landscape scales^{135,136}, and model performance improves when combined with
424 multispectral EO sensors¹³⁷. By predicting the dissimilarity of sites alongside an expected
425 species-area relationship, GDM can also be used to estimate the proportion of biodiversity
426 retained regionally (**Box 3** in main text). This has numerous conservation applications (e.g.
427 protected areas effectiveness – Aichi Target 11¹³⁸), as well as quantifying the biodiversity
428 left regionally (gamma diversity) to support ecosystem services¹³⁹. If the identity of species
429 composition is still desired, GDM can be combined with a model of alpha diversity to
430 estimate the probable species composition of every cell in a landscape¹⁴⁰. Furthermore,
431 ecological processes like dispersal, growth rates, and metacommunity dynamics have been
432 incorporated to predict ecosystem function and to rank management actions^{134,141}.

433 *Sampling design.* – For a given sampling effort, careful survey design can improve the
434 accuracy and reliability of biodiversity models. For example, although we may be interested
435 in the different species assemblages that each contribute to carbon storage in forests (e.g.
436 large frugivorous mammals, isopods, and saprotrophic fungi; **Box 2** in main text), we would
437 not sample for these disparate taxa at the same spatial grain¹⁴². For example, within the
438 home range of a single monkey troupe, the composition of saprotrophic fungi might exhibit
439 high levels of turnover across wood from different tree species. Fungi thus need to be
440 sampled at a finer spatial grain than do mammals, and soil fauna might need to be sampled
441 even more finely again. The grain of sampling should therefore try to match the grain at
442 which environmental heterogeneity creates different habitats, but for efficiency, should also
443 aggregate across points whose composition only varies due to stochastic fluctuations.
444 Once the scale of analysis has been chosen, the sampling strategy can be adjusted to

445 ensure that biological samples represent an equivalent area effectively. For example, how
446 many soil cores need to be sequenced to estimate the diversity of fungi within a forest plot?
447 Scaling relationships like species-area curves can be a useful shortcut to compare
448 community-level characteristics (alpha or beta diversity), but they cannot identify which
449 species were missed. Instead, the differences in sampling effort, including the area sampled
450 (e.g. number of quadrats), could be accounted for explicitly by species' detectability in
451 community occupancy models¹⁰⁹. Finally, it is important that samples capture the full range
452 and variability of environments across the region of study, especially where environmental
453 differences lead to higher turnover¹³⁰. This is particularly true of finite resources that
454 become limiting, such as soil moisture gradients that determine vegetation succession in
455 arid biomes, but are less important to predicting turnover in the wet tropics. These
456 decisions can be guided by expert opinion and existing survey data, but pilot studies may
457 be required at multiple spatial and temporal resolutions, before settling on a single strategy.

458 In addition to the pathways that we have described above and in the Main Text (Figure 3),
459 there of course exist other methods to model communities, which take into explicit account
460 biological mechanisms such as demography, dispersal, evolution, and specialist
461 interactions^{143,144}. We have not covered these methods because they require much more
462 input data¹⁴⁵ and thus are limited in their applicability, although when available, all
463 information should of course be exploited. We reiterate that species co-occurrence
464 matrices, latent variables, phylogenetic structure, and ecological functions can all be
465 extracted from the three statistical pathways in Figure 3, and these provide an efficient way
466 to generate causal hypotheses for further, targeted investigation.

467 **Acknowledgments for individual authors**

468 D. W. Yu was supported by the National Natural Science Foundation of China (31400470,
469 41661144002, 31670536, 31500305, GYHZ1754), the Ministry of Science and
470 Technology of China (2012FY110800), the University of East Anglia, and the State Key

471 Laboratory of Genetic Resources and Evolution at the Kunming Institute of Zoology
472 (GREKF13-13, GREKF14-13, GREKF16-09).

473 M. T. P. Gilbert was supported by Danish National Research Foundation grant DNRF94 and
474 Lundbeck Foundation grant R52-5062.

475 A. Wilting was supported by the German Federal Ministry of Education and Research grant
476 BMBF FKZ: 01LN1301A.

477 L. Matthews, C. A. Cobbold, and R. Reeve were supported by BBSRC grant
478 BB/N013336/1.

479 A. P. Vogler was supported by the Biodiversity Initiative of the Natural History Museum. The
480 Initiative funded an international symposium ‘Tropical Biodiversity in the 21st Century’
481 (June 2013) that convened researchers in tropical biology, EO and molecular
482 taxonomy.

483 A. Zlinszky was funded by the PD 115833 grant of the Hungarian Science Fund (OTKA)

484 M. Herold was supported by the Global Forest Observation Initiative (GFOI) research and
485 development programme and the Global Observations of Forest Cover and Land
486 Dynamics (GOFC-GOLD) project office funded by the European Space Agency.

487 C. Martius and M. Herold were supported by the Norwegian Agency for Development
488 Cooperation (Norad) and the International Climate Initiative (IKI) of the German Federal
489 Ministry for the Environment, Nature Conservation, Building and Nuclear Safety
490 (BMUB), and the CGIAR Research Program on Forests, Trees and Agroforestry (CRP-
491 FTA) with financial support from the donors to the CGIAR Fund. This work of M.
492 Herold was further supported by the Global Forest Observation Initiative (GFOI)
493 research and development programme and the sponsor of Global Observations of
494 Forest Cover and Land Dynamics (GOFC-GOLD). Kim Calders and Jose Gonzales are
495 acknowledged for providing the TLS data for the Elephant in Gabon.

496 B. C. Emerson was supported by Spanish MINECO grant CGL2013-42589-P, co-financed
497 by FEDER, and Spanish MAGRAMA grant S20141203_002597 from the Organismo
498 Autonomo Parques Nacionales.

499 J. R. Olson and T. W. Rodgers are supported by NASA grant NNX14AC40G and
500 NNX15AR79G.

501 K. Bohmann was supported by The Danish Council for Independent Research grant DFF –
502 5051-00140.

503 M.J. Wooster was supported by the NERC National Center for Earth Observation (NCEO),
504 UK.

505 B. Cole was supported by the NERC Biodiversity and Ecosystem Services Sustainability
506 (BESS) program.

507 H. Balzter was supported by the NERC Biodiversity and Ecosystem Services Sustainability
508 (BESS) program and the NERC National Center for Earth Observation (NCEO), UK.

509

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